

Under What Assumptions do Site-by-Treatment Instruments

Identify Average Causal Effects?

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ABSTRACT

The increasing availability of data from multi-site randomized trials provides a potential opportunity to use instrumental variables methods to study the impacts of multiple hypothesized mediators of the effect of a treatment. We describe nine assumptions needed to identify the impacts of multiple mediators when using site-by-treatment interactions to generate multiple instruments. Three of these assumptions are unique to the multiple-site, multiple-mediator case: 1) the assumption that the mediators act in parallel (no mediator affects another mediator); 2) the assumption that the site-average effect of the treatment on each mediator is independent of the site-average effect of each mediator on the outcome; and 3) the assumption that the site-by-compliance matrix has sufficient rank. The first two of these assumptions are non-trivial and cannot be empirically verified, suggesting that multiple-site, multiple-mediator instrumental variables models must be justified by strong theory.

1. INTRODUCTION

In canonical applications of the instrumental variable method, exogenously determined exposure to an instrument (such as random assignment to a treatment condition) induces exposure to a mediating process that in turn causes a change in a later outcome. A crucial assumption known as the exclusion restriction is that the hypothesized instrument can influence the outcome only through its influence on exposure to the mediator of interest (Heckman & Robb, 1985b; Imbens & Angrist, 1994). It may be the case, however, that multiple mediators operate jointly to influence the outcome, in which case a single instrument will not suffice to identify the causal effects of interest.

To cope with this problem, analysts have recently exploited the fact that a causal process is often replicated across multiple sites, generating the possibility of multiple instruments in the form of site-by-instrument interactions. These multiple instruments can, in principle, enable the investigator to identify the impact of multiple processes regarded as the mediators of the effect of a treatment (or, equivalently, of multiple programs or treatments regarded as the mediators of the effect of an instrument). Kling, Liebman, and Katz (2007), for example, used random assignment in the Moving to Opportunity (MTO) study as an instrument to estimate the impact of neighborhood poverty on health, social behavior, education, and economic self-sufficiency of adolescents and adults. Reasoning that the instrument might affect outcomes through mechanisms other than neighborhood poverty, they control for a second mediator, use of the randomized treatment voucher. To do so, they capitalize on the replication of the MTO experiment in

five cities, generating ten¹ instruments (“site-by-randomization interactions”) to identify the impact of the two mediators of interest, neighborhood poverty and experimental compliance. Using a similar strategy, Duncan, Morris, and Rodrigues (forthcoming) use data from 16 implementations of welfare-to-work experiments to identify the impact of family income, average hours worked, and receipt of welfare as mediators.

Clearly, this strategy for generating multiple instruments has potentially great appeal in research on causal effects in social science. For example, Spybrook (2008) found that, among 75 large-scale experiments funded by the US Institute of Education Sciences over the past decade, the majority were multi-site studies in which randomization occurred within sites. In principle, these data could yield a wealth of new knowledge about causal effects in education policy. It is essential, however, that researchers understand the assumptions required to pursue this strategy successfully. To date, we know of no complete account of these assumptions.

Our purpose therefore is to clarify the assumptions that must be met if this “multiple site, multiple mediator” instrumental variables strategy (hereafter MSMM-IV) is to identify the average causal effects (ATE) in the populations of interest. For simplicity of exposition, and corresponding to the applications of MSMM-IV to date, we consider the case of where a single treatment T operates through a set of mediators $\mathbf{M} = \{M_1, M_2, \dots, M_p\}$, which are linearly related to an outcome Y . We conclude that, in addition to the assumptions typically required in the single-site, single-instrument, single-mediator case, three additional assumptions are required in the MSMM-IV case.

¹ The five sites generate ten site-by-treatment interactions as instruments because there were three (randomly assigned) treatment conditions per site.

We begin by delineating the assumptions required for identification in the case of a single instrument and a single mediator within a single-site study. Unlike Angrist, Imbens, and Rubin (1996) (AIR), we consider the general case where both the treatment and the mediator may be continuous or multi-valued. In this general case, the assumptions required for identification of the average treatment effect differ somewhat from those AIR (1996) describe for the binary treatment and binary mediator case. We link our discussion to recent papers describing the correlated random coefficient (CRC) model, and show that the average treatment effect in the CRC model is identified by instrumental variables using a weaker assumption than that described by Heckman and Vytlačil (1998) and Wooldridge (2003).

Following a discussion of the single, site, single mediator case, we then consider the case of multiple sites with a single mediator, delineating the assumptions required in this case. We then turn our attention to the case of primary interest: the MSMM-IV design. We specify a set of nine assumptions required for the MSMM-IV model to identify the average treatment effects of the mediators, three of which are specific to the MSMM-IV case, and which we discuss in some detail.

2. THE SINGLE-SITE, SINGLE-MEDIATOR CASE

Suppose that each participant in a single-site study is exposed to an instrument T taking on values in the domain $\mathbb{T} \subset \mathbb{R}$. We often consider instruments taking on values in the domain $\mathbb{T} = \{0,1\}$, where $T = 1$ if the individual is assigned to the “treatment” condition or $T = 0$ if the participant is assigned to the alternative “control” condition. More generally, however, T may be multi-valued or continuous.

In order to define a set of causal estimands of interest, we require the assumption that an individual's potential outcomes depend only on the treatment condition and mediator conditions to which that particular individual is exposed (and not on the treatment and mediator conditions of others), known as the Stable Unit Treatment Value Assumption (SUTVA) (Rubin, 1986). In the standard potential outcomes framework, we typically require a single SUTVA assumption stating that one individual's potential outcomes do not depend on others' treatment status. In the IV model, however, the presence of three variables of interest—the treatment T , a mediator M , and an outcome Y —necessitates a pair of such assumptions (Angrist et al., 1996), stated formally below.

Assumption (i): Stable unit treatment value assumptions (SUTVA):

- (i.a) Each unit i has one and only one potential value of the mediator M for each treatment condition t : that is, for a population of size N , $m_i(t_1, t_2, \dots, t_N) = m_i(t_i)$ for all $i \in \{1, 2, \dots, N\}$.
- (i.b) Each unit i has one and only one potential outcome value of Y for each pair of values of treatment condition t and mediator value m : that is, for a population of size N , $y_i(t_1, t_2, \dots, t_N, m_1, m_2, \dots, m_N) = y_i(t_i, m_i)$ for all $i \in \{1, 2, \dots, N\}$.

Given the SUTVA assumptions, we can represent the potential outcome Y for a participant who experiences treatment t and mediator value $m(t)$ as $y(t, m(t))$ (we drop the subscript i throughout the remainder of this paper except when necessary for clarity). Our second assumption is that T affects Y only through its impact on the mediator, M . This is the standard exclusion restriction assumption:

Assumption (ii): Exclusion restriction:

$$y(t) = y(t, m(t)) = y(m(t)).$$

The exclusion restriction combined with the second SUTVA assumption (i.b) implies a third SUTVA condition: (i.c) Each unit i has one and only one potential outcome value of Y for each value of the mediator m : that is, for a population of size N , $y_i(m_1, m_2, \dots, m_N) = y_i(m_i)$ for all $i \in \{1, 2, \dots, N\}$.

The SUTVA assumptions are necessary in order to define the causal estimands of interest. If the treatment variable is binary, for example, the first SUTVA assumption (i.a) implies that we can define the person-specific casual effect of the treatment on M as $\Gamma = m(1) - m(0)$.² If, however, the treatment is not binary, it will be useful to assume that the person-specific effect of T on M is linear in T , in which case $\Gamma = m(t) - m(t - 1)$:

Assumption (iii): Person-specific linearity of the mediator M in T : The person-specific effect of T on mediator M is linear. That is, $m(t) = m(0) + t\Gamma$.

Likewise, it will be useful to assume that the person-specific effect of M on Y is linear in M . In this case, the third SUTVA condition (i.c) implies that we can define the

² Note that if both T and M are binary, taking on values of 0 or 1, then $\Gamma \in \{-1, 0, 1\}$. In this case, Angrist, Imbens, and Rubin (Angrist et al., 1996) assume that there do not exist both individuals for whom $\Gamma = 1$ and individuals for whom $\Gamma = -1$ (this is the no “defiers” assumption, in their terminology; also called the monotonicity assumption). We will not require the monotonicity assumption, for reasons we discuss below.

person-specific casual effect of the mediator Y as $\Delta = y(m) - y(m - 1)$:

Assumption (iv): Person-specific linearity in m : the person-specific effect of the mediator $m(t)$ on Y is linear. That is, $y(m(t)) = y(m = 0) + m\Delta$.

The combination of (ii), (iii), and (iv) implies that the person-specific effect of T on Y is linear in T :

$$\begin{aligned} y(m(t)) &= y(m(0) + t\Gamma) \\ y(t) &= y(m = 0) + [m(0) + t\Gamma]\Delta \\ y(t) &= [y(m = 0) + m(0)\Delta] + t\Gamma\Delta \end{aligned}$$

Thus, defining B as the person-specific effect of T on Y , we can relate the person-specific effects of T on M and of M on Y to the person-specific effect of T on Y by

$$y(t) - y(t - 1) = B = \Gamma\Delta. \tag{1}$$

Let us define the population average intent-to-treat effect (ITT) of interest here as $E(B) = \beta$. Similarly, the average causal effect of T on the mediator M (the “average compliance”) is $E(\Gamma) = \gamma$; and $E(\Delta) = \delta$ is the average treatment effect (ATE) of M on Y .

This ATE is typically of central interest in studies using instrumental variables. Taking the expectation of (1), we have

$$E(B) = \beta = E(\Delta\Gamma) = \delta\gamma + Cov(\Delta, \Gamma). \tag{2}$$

Two additional assumptions allow us to express the ATE as ratio of the ITT effect to the average compliance. These are:

Assumption (iv): No person-specific compliance-effect covariance: $Cov(\Delta, \Gamma) = 0$.

Assumption (v): Effectiveness of the instrument: $\gamma \neq 0$.

The no compliance-effect covariance assumption means that the extent to which treatment status affects an individual's value of the mediator M is uncorrelated with the extent to which M affects the individual's outcome Y . This may not always be a plausible assumption. For example, if individuals have some knowledge of how much they will benefit from an intervention, those for whom the intervention is most effective may comply more fully with it, if offered it, than those for whom the intervention is less effective.

The instrument effectiveness assumption simply means that the average effect of the treatment on the mediator is non-zero (though the effect may be positive for some individuals and negative for others). Together, these two assumptions enable us to write Equation (2) as

$$\delta = \frac{\beta}{\gamma}, \quad \gamma \neq 0. \tag{3}$$

The six assumptions derived so far enable us to equate the ATE to the ratio β/γ . The parameters β and γ are not directly observable, however, because they are means of differences in counterfactual outcomes. If we are willing to assume that persons are assigned ignorably to treatments $T = t$ for $t \in \mathbb{T}$, as would be true in a randomized experiment, we can identify (3) from sample data. We therefore add our seventh and final

assumption in this section:

Assumption (vii): Ignorable treatment assignment: $T \perp Y(t), T \perp M(t), t \in \mathbb{T}$.

Applying the no-compliance-effect assumption (v) and ignorable treatment assignment (vii), we can equate the ITT effect (2) to the estimable quantity $E(Y|T = t) - E(Y|T = t - 1)$, yielding

$$\begin{aligned}
 E(Y|T = t) - E(Y|T = t - 1) &= E(Y(t)|T = t) - E(Y(t - 1)|T = t - 1) \\
 &= E(Y(t)) - E(Y(t - 1)) && \text{(vii)} \\
 &= E(Y(t) - Y(t - 1)) \\
 &= E[B] = \beta = \delta\gamma + Cov(\Delta, \Gamma) \\
 &= \delta\gamma. && \text{(v)}
 \end{aligned}
 \tag{4}$$

Without the no compliance-effect-covariance assumption (v), but allowing all other assumptions, the instrumental variable estimand in a population of size N is

$$\frac{\beta}{\gamma} = \frac{[\delta\gamma + Cov(\Delta, \Gamma)]}{\gamma} = \delta + \frac{Cov(\Delta, \Gamma)}{\gamma} = \frac{\sum_{i=1}^N \Gamma_i \Delta_i}{\sum_{i=1}^N \Gamma_i}.
 \tag{5}$$

Equation (5) may be regarded as a “compliance-weighted average treatment effect” (CWATE) because each person’s treatment effect Δ is weighted by his or her compliance, Γ .

The magnitude of the bias in the CWATE relative to the ATE is determined not only by the covariance of Γ and Δ , but also by the inverse of γ . When γ is small, any bias due to compliance-effect covariance will be exacerbated.

Heckman and colleagues have argued that this CWATE may not be an economically or policy relevant parameter, in part because it is dependent on the specific instrument that induces exposure to the mediator (Heckman & Robb, 1985a, 1986; Heckman, Urzua, & Vytlacil, 2006). Because Γ is instrument-specific, the IV estimand in this case is likewise instrument-specific when the no compliance-effect covariance assumption fails.

The Case of Binary T and M

Angrist, Imbens, and Rubin (1996) consider the case where both T and M are binary. In this case, the population may contain at most four types of individuals: “compliers,” for whom $\Gamma = m(1) - m(0) = 1 - 0 = 1$; “never-takers,” for whom $\Gamma = 0 - 0 = 0$; “always-takers,” for whom $\Gamma = 1 - 1 = 0$; and “defiers,” for whom $\Gamma = 0 - 1 = -1$. The monotonicity or “no defiers” assumption,

$$m_i(1) \geq m_i(0), \quad \forall i \in \{1, \dots, N\},$$

eliminates the possibility of defiers. Under this assumption, we can simplify the expression for the CWATE of (5) to

$$\frac{\beta}{\gamma} = \frac{\sum_{i=1}^{N_c} \Delta_i}{N_c} = E(\Delta | \Gamma = 1) \equiv \delta_c$$

(6)

where N_c is the number of compliers in the population. Angrist and Imbens (1996) termed δ_c the “local average treatment effect” (LATE), also known as the average treatment effect on the compliers or the complier average treatment effect (CATE). Equation (6) shows that the LATE is a special case of the CWATE when both T and M are binary and the monotonicity assumption holds. Angrist, Imbens, and Rubin (1996) did not note the no compliance-effect covariance assumption (iv) because it is not required to obtain the LATE.³

Note, however, that monotonicity is not an assumption required for the identification of the ATE parameter δ . If there are defiers (or more generally, if there are both individuals for whom $\Gamma < 0$ and individuals for whom $\Gamma > 0$), Equation (5) plus the assumptions that $Cov(\Gamma, \Delta) = 0$ and $\gamma \neq 0$ ensure that $\frac{\beta}{\gamma} = \delta$.

The Correlated Random Coefficients Model

Above we note that the assumption that the no compliance-effect covariance assumption is necessary for instrumental variables estimators to identify the average treatment effect in the population. We digress here briefly to relate this assumption to the specific application of the instrumental variables model in the case of the correlated random coefficients (CRC) model discussed by Heckman and Vytlacil (1998) and Wooldridge (2003). In the CRC model, the effect Δ of a causal variable M on an observable outcome Y varies across individuals, as in the model

³ In some settings (e.g., Little & Yau, 1998), participants assigned to the control cannot gain access to the mediator, that is $\Pr(m(0) = 0) = 1.0$. In this case, there are no “always-takers.” We then see that LATE becomes the “treatment effect on the treated” (TOT), that is $E(\Delta|m = 1) \equiv \delta_{TOT}$.

$$Y_i = \alpha_i + \Delta_i M_i.$$

Using the potential outcomes framework, $\alpha_i = y_i(m_i = 0)$. Both Heckman and Vytlačil (1998) and Wooldridge (2003) introduce an instrumental variable T satisfying the standard exclusion restriction and ignorable assignment conditions, and show that under the assumption that $Cov(\Delta_i, M_i | \mathbf{X} = \mathbf{x}, T = t) = c$, where \mathbf{X} is some vector of covariates, and c is a constant, instrumental variables estimators will yield consistent estimates of $\delta = E[\Delta_i]$.

Note that our assumption (v) above is weaker than the Heckman and Vytlačil and Wooldridge assumption. Using the potential outcomes framework, we can write

$$m(\mathbf{x}, t) = m(\mathbf{x}, 0) + t\Gamma.$$

For simplicity of exposition, we assume here that Γ does not depend on \mathbf{x} ; if it does, we could include interactions between t and \mathbf{x} as additional instruments with no loss of generality. We now write the HV/W assumption regarding the conditional covariance of the mediator and the effect as

$$\begin{aligned} Cov(M, \Delta) | \mathbf{x}, t &= Cov(m(\mathbf{x}, 0), \Delta) | \mathbf{x}, t + t \cdot Cov(\Gamma, \Delta) | \mathbf{x}, t \\ &= Cov(m(\mathbf{x}, 0), \Delta) | \mathbf{x} + t \cdot Cov(\Gamma, \Delta) | \mathbf{x} \\ &= c. \end{aligned}$$

Note that we drop the t from the condition, because t is assumed ignorably assigned, conditional on \mathbf{x} . In order for this expression to be constant across values of \mathbf{x} and t , we require both $Cov(m(\mathbf{x}, 0), \Delta) | \mathbf{x} = c$ and $Cov(\Gamma, \Delta) | \mathbf{x} = 0$. The latter is our no compliance-effect covariance assumption (v). Thus, the HV/W assumption is stronger than our no compliance-effect covariance assumption because it implies the additional assumption that the covariance between the counterfactual values of the mediator in the case when $t = 0$

and the effect of the mediator is constant across values of \mathbf{x} . However, our result above demonstrates that we require only that $Cov(\Gamma, \Delta)|\mathbf{x} = 0$; it is not necessary that $Cov(m(\mathbf{x}, 0), \Delta)|\mathbf{x}$ be constant across values of \mathbf{x} .

Our formulation above clarifies that IV estimators rely on an assumption regarding the relationship between the effects of the instrument on the mediator and the effects of the mediators on the outcomes, not an assumption about the relationship between the observed levels of the mediator and its effects. This is because the IV model relies for identification on the fact that the instrument induces some exogenous variation in the mediator; the amount of this variation must be independent of the effects of the mediator in order to avoid bias in the IV estimator. By focusing on the relationship between the observed values of the mediator and its (unobserved) effects, Heckman and Vytlacil (1998) and Woolridge (2003) make a stronger assumption than is necessary. A correlation between the observed values of a mediator and its effects that arises solely from a correlation between baseline levels of the mediator and its effects will not cause bias in the instrumental variables estimates.

Summary of Single-Site, Single Mediator IV Assumptions

Approaching the instrumental variable model from a potential outcomes framework is particularly useful when we allow treatment effects to be heterogeneous. After imposing assumptions (i)-(iv) (SUTVA, exclusion restriction, and linearity), this framework reveals the importance of (v), the no-compliance-effect-covariance assumption along with the conventional assumptions (vi) and (vii) (effectiveness of the instrument and ignorable treatment assignment). If (v) fails, the instrumental variable estimand is a compliance

weighted average treatment effect (CWATE): those persons whose mediator is most affected by the instrument will be assigned the greatest weight in the estimand. In the case of a binary instrument and binary mediator, we can replace the “no compliance-covariance assumption” with a monotonicity assumption; in this case CWATE=LATE, the local average treatment effect. In addition, if the members of the control group can be assumed to have a known and constant value of the mediator, LATE=TOT, the treatment effect on the treated.

3. THE IV MODEL WITH MULTIPLE SITES AND A SINGLE MEDIATOR

We next consider the case of a multi-site study, where within each site each participant is exposed to an instrument T , which may influence Y through a single mediator M . In this case, if we accept that assumptions (i)-(iv) (SUTVA, exclusion restriction, and linearity) hold within each site, we can write Equation (2) as

$$E(B|S = s) = \beta_s = E(\Delta\Gamma|S = s) = \delta_s\gamma_s + Cov_s(\Delta, \Gamma), \tag{7}$$

where s indexes sites and where $E[\Delta|S = s] = \delta_s$ and $E[\Gamma|S = s] = \gamma_s$. Pooling (7) across sites, we have

$$\begin{aligned} E(B) = \beta &= E(\beta_s) = E(\delta_s\gamma_s + Cov_s(\Delta, \Gamma)) \\ &= \delta\gamma + Cov(\delta_s, \gamma_s) + E(Cov_s(\Delta, \Gamma)). \end{aligned} \tag{8}$$

Now, rather than the single assumption that $Cov(\Delta, \Gamma) = 0$, we need two compliance-effect covariance assumptions:

Assumption (v.a): No average within-site compliance-effect covariance: $E(\text{Cov}_s(\Delta, \Gamma)) = 0$. A simpler, but stronger assumption, is that there is no within-site compliance-effect covariance in any site: $\text{Cov}_s(\Delta, \Gamma) = 0$ for all s .

Assumption (v.b): No between-site compliance effect covariance: $\text{Cov}(\delta_s, \gamma_s) = 0$.

These assumptions, together with assumption (vi) (instrument effectiveness), enable us to write (8) as

$$\delta = \frac{\beta}{\gamma}, \quad \gamma \neq 0, \tag{3}$$

as above. Assumption (vii) (ignorable treatment assignment within sites) then enables us to identify the causal effect δ from sample data.

4. THE IV MODEL WITH MULTIPLE SITES AND MULTIPLE MEDIATORS

We now consider the case of particular interest for this paper, the case where subjects within a multi-site study are exposed to a treatment T , which may influence Y through P distinct mediators M_1, M_2, \dots, M_P . We first assume that both SUTVA assumptions hold (i.a and i.b)) with respect to the vector of P mediators:

Assumption (i): Stable unit treatment value assumptions (SUTVA):

- (i.a) Each unit i has one and only one potential value of the vector of mediators

$\mathbf{m}_i = \{m_{1i}, m_{2i}, \dots, m_{pi}\}$ for each treatment condition t : that is, for a population of size N , $\mathbf{m}_i(t_1, t_2, \dots, t_N) = \mathbf{m}_i(t_i)$ for all $i \in \{1, 2, \dots, N\}$.

- (i.b) Each unit i has one and only one potential outcome value of Y for each treatment condition t and each vector of mediator values \mathbf{m}_i : that is, for a population of size N , $y_i(t_1, t_2, \dots, t_N, \mathbf{m}_1, \mathbf{m}_2, \dots, \mathbf{m}_N) = y_i(t_i, \mathbf{m}_i)$ for all $i \in \{1, 2, \dots, N\}$.

We next assume that assignment to T influences Y only through the list of P distinct and observable mediators M_1, M_2, \dots, M_P . Specifically, each participant has potential mediator values $m_1(t), m_2(t), \dots, m_p(t)$ for $t \in \mathbb{T}$. The exclusion restriction now requires that T affects Y only through its effects on one or more of the mediators. That is:

Assumption (ii): Exclusion restriction: The treatment T affects Y only through its impact on the set of P mediators, $\mathbf{M} = \{M_1, M_2, \dots, M_P\}$. That is, $Y(t) = Y(t, \mathbf{m}(t)) = Y(\mathbf{m}(t))$.

As above, we also assume person-specific linearity of each M in T (iii) and linearity of Y in each of the mediators (iv). Specifically, we assume that the outcome Y is a linear function of the mediators, and that there are no interactions among the mediators.

Assumption (iii): Person-specific linearity of each mediator in T : The person-specific effect of T on each mediator M_p is linear. That is, $m_p(t) = m_p(0) + t\Gamma_p$ for each p .

Assumption (iv): Person-specific linearity of Y in \mathbf{M} : The person-specific effect of each mediator M_p on Y is linear. That is, $Y(\mathbf{m}) = Y(\mathbf{m} = \mathbf{0}) + \sum_{p=1}^P m_p \Delta_p$.

These imply, respectively, that the person-specific causal effect of T on M_p is $\Gamma_p = m_p(t) - m_p(t - 1)$, and that the person-specific causal effect of M_p on Y is $\Delta_p = y(m_p) - y(m_p - 1)$, for all $p \in 1, 2, \dots, P$. As above, the person-specific causal effect of T on Y is $B = y(t) - y(t - 1)$. The observed outcome is $y(t) = y(0) + tB$.

We next assume that assignment to T does not influence a given mediator M_p through any other mediator M_q . That is, the mediators do not influence one another. This is required so that the estimation of the effects of a given mediator M_q on Y are not confounded with the effects of another mediator M_p .

Assumption (v): Parallel mediators:

$$m_p(t, m_1, \dots, m_{p-1}, m_{p+1}, \dots, m_P) = m_p(t) \text{ for all } p \in 1, 2, \dots, P.$$

Together, the five assumptions above define the person-specific intent-to-treat effect as

$$\begin{aligned} B &= y(t) - y(t - 1) \\ &= y(m_1(t), m_2(t), \dots, m_P(t)) - y(m_1(t - 1), m_2(t - 1), \dots, m_P(t - 1)) \\ &= \sum_1^P \Delta_p \Gamma_p. \end{aligned} \tag{9}$$

Equation (9) says that the person-specific effect of T on Y can be written as the sum of the products of the person-specific effects of T on each mediator and the person-specific effects of that mediator on the Y (below we discuss the implications of a failure of the parallel

mediator assumption). Taking the expectation of (9) over the population within a site s yields

$$E(B|S = s) = \beta_s = E\left(\sum_1^P \Delta_p \Gamma_p | S = s\right) = \sum_1^P \delta_{ps} \gamma_{ps} + \sum_1^P \text{Cov}_s(\Delta_p, \Gamma_p), \quad (10)$$

where δ_{ps} and γ_{ps} are the average effect of M_p on Y in site s and the average effect of T on M_p in site s , respectively; and where $\text{Cov}_s(\Delta_p, \Gamma_p)$ is the covariance between Δ_p and Γ_p in site s .

We next assume no within-site covariance between Δ^p and Γ^p for each mediator p :

Assumption (vi): No within-site compliance-effect covariance:

$$\text{Cov}_s(\Delta_p, \Gamma_p) = 0, \text{ for all } p \text{ and } s.$$

We now have, for each site s , the equation

$$\begin{aligned} \beta_s &= \sum_1^P \delta_{ps} \gamma_{ps} \\ &= \sum_1^P \delta_p \gamma_{ps} + \sum_1^P (\delta_{ps} - \delta_p) \gamma_{ps} \\ &= \sum_1^P \delta_p \gamma_{ps} + \omega_s, \end{aligned} \quad (11)$$

where δ_p is the average, across sites, of the δ_{ps} 's and $\omega_s = \sum_1^P (\delta_{ps} - \delta_p) \gamma_{ps}$.

Equation (11) shows that, under the assumptions above, the site-average β 's can be expressed as a linear combination of the site-average γ_p 's plus some site-specific residual error term. The coefficients δ_p on the γ_{ps} terms are the parameters of interest—the average effects of the mediators on the outcome Y . Equation (11) suggests that the δ_p 's may be estimated with a multiple linear regression estimator, under the assumption that the errors have an expected value of zero, given the γ_{ps} 's. This insight suggests we require an assumption regarding the independence of the γ_{ps} 's and δ_{ps} 's:

Assumption (vii): Between-site compliance-effect independence: The site-average compliance of each mediator is independent of the site-average effect of each mediator. That is,

$$E[\delta_{qs} | \gamma_{1s}, \gamma_{2s}, \dots, \gamma_{Ps}] = E[\delta_{qs}] = \delta_q \text{ for all } q \in 1, \dots, P.$$

Note that the assumption that the site-mean compliance is independent of the site-mean effect is stronger than an assumption of no compliance-effect covariance (the latter requires only no linear association between compliance and effect; the former requires no association whatsoever). Moreover, note that this assumption requires not only that there be no compliance-effect association for a given mediator, but also that there be no cross-mediator compliance-effect association. That is, the site-average effect of T on a given mediator q cannot be correlated with the site-average effect of any mediator p on Y .

Under this assumption, we can write the expected value of the error ω_s in (11) as

$$\begin{aligned}
E[\omega_s | \gamma_{1s}, \gamma_{2s}, \dots, \gamma_{Ps}] &= E \left[\sum_{q=1}^P (\delta_{qs} - \delta_q) \gamma_{qs} \middle| \gamma_{1s}, \gamma_{2s}, \dots, \gamma_{Ps} \right] = 0 \\
&= \sum_{q=1}^P \gamma_{qs} \cdot E[(\delta_{qs} - \delta_q) | \gamma_{1s}, \gamma_{2s}, \dots, \gamma_{Ps}] \\
&= \sum_{q=1}^P \gamma_{qs} \cdot E[(\delta_{qs} - \delta_q)] \\
&= 0.
\end{aligned}$$

In order that Equation (11) identify the δ_p 's, we must know β_s 's and the γ_{ps} 's. Although these cannot be observed from the data, under the assumption of ignorable within-site treatment assignment, each of the β_s 's and the γ_{ps} 's can be estimated from the sample data.

Thus, as above, we require:

Assumption (viii): Ignorable within-site treatment assignment: The assignment of the instrument (the treatment, in our notation) must be independent of the potential outcomes within each site: $T \perp Y(t) | s$, $T \perp \mathbf{m}(t) | s$, $\forall t \in \mathbb{T}, s \in \{1, \dots, S\}$.

Given the β_s 's and the γ_{ps} 's, we can estimate the δ_p 's, so long as the site-by-mediator compliance matrix has sufficient rank. We formalize this assumption below:

Assumption (ix): Site-by-mediator compliance matrix has sufficient rank. In particular, if G is the $S \times P$ matrix of the γ_{ps} 's, we require $\text{rank}(G) = P$. This implies three specific conditions:

(ix.a) The compliance of at least $P - 1$ of the mediators varies across sites. That is,

$$\text{Var}(\gamma_{ps}) = 0, \text{ for at most one } p \in \{1, 2, \dots, P\}.$$

(ix.b) There are at least as many sites as mediators: $P \leq S$.

(ix.c) There is some subset of Q site-specific compliance vectors,

$$\mathbf{\gamma}_s = \{\gamma_{1s}, \gamma_{2s}, \dots, \gamma_{Ps}\}, \text{ where } S \geq Q \geq P, \text{ that are linearly independent.}$$

The sufficient rank assumption is a generalization of the familiar instrument effectiveness assumption (assumption (vi) in the first section). Note that when there is a single mediator ($P = 1$), the site-by-mediator compliance matrix will have rank 1 so long as $\gamma_{1s} \neq 0$ for at least one site s (the average compliance across sites may be zero, as long as it is not zero in every site). Thus, when there is a single site and a single mediator, the sufficient rank assumption is therefore identical to the usual condition that the treatment have a non-zero average impact on the mediator.

5. DISCUSSION

Summary of Multiple-Site, Multiple-Mediator IV Assumptions

To summarize, in the case of a multi-site study in which an treatment T may affect the outcome Y through multiple mediators, we require a number of assumptions in order to identify the average causal effects of the mediators using MSSM-IV methods. These are:

- (i) Stable unit treatment value assumptions
- (ii) Exclusion restriction
- (iii) Person-specific linearity of the mediators with respect to the treatment

- (iv) Person-specific linearity of the outcome with respect to the mediators
- (v) Parallel mediators
- (vi) Zero within-site compliance-effect covariance for each mediator
- (vii) Between-site cross-mediator compliance-effect independence
- (viii) Within-site ignorable treatment assignment
- (ix) Compliance matrix has sufficient rank

Note that six of these assumptions—SUTVA, the exclusion restriction, the two linearity assumptions, zero within-site compliance-effect covariance, and ignorable treatment assignment—are identical to those required for the single-site, single-instrument, single-mediator case (though often the two linearity assumptions are ignored because they are met trivially when the instrument and mediators are binary). A seventh assumption—the sufficient rank assumption—is equivalent to the instrument effectiveness assumption when there is a single site and single mediator, as we note above. Assumptions (v), (vii), and (ix) are specific to the multiple-site, multiple-mediator case. We discuss these assumptions in more detail below.

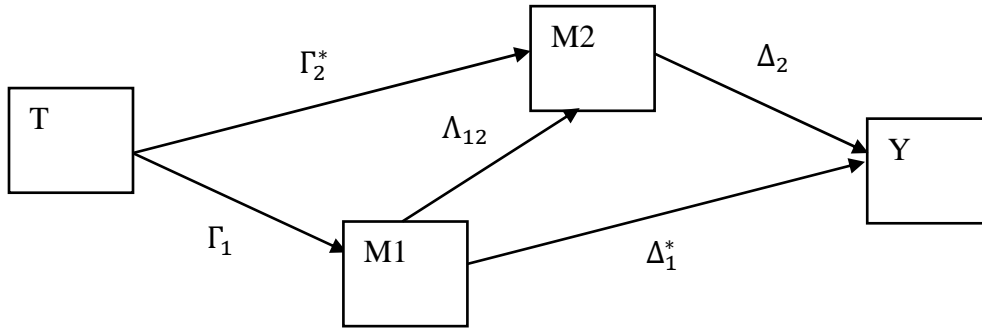
The Parallel Mediators Assumption

The assumption that the mediators impact an outcome in parallel is a non-trivial assumption. Consider the Duncan, Morris, and Rodrigues (forthcoming) paper cited above. In this study, eight random-assignment welfare-to-work experiments were used to estimate the impact of three hypothesized mediators of the programs: income, hours worked, and welfare receipt. The multiple-site, multiple mediator IV models used assume

that the none of these mediators affects the others. However, this is an implausible assumption, given that both hours worked and welfare receipt are clearly linked to income.

For illustration, consider a simple case in which a treatment T affects Y through two mediators, $M1$ and $M2$, one of which affects the other, as shown in the structural diagram below:

Figure 1:



Let Γ_1 and Γ_2 be the person-specific effects of T on $M1$ and $M2$, respectively. Note that

$$\Gamma_2 = \Gamma_2^* + \Gamma_1 \Lambda_{12},$$

where Γ_2^* is the direct effect of T on $M2$ (the effect not mediated by $M1$), and Λ_{12} is the effect of $M1$ on $M2$. Likewise, let Δ_1 and Δ_2 be the effects of $M1$ and $M2$ on Y , respectively.

Note that

$$\Delta_1 = \Delta_1^* + \Lambda_{12} \Delta_2,$$

where Δ_1^* is the direct effect of $M1$ on Y (the effect not mediated by $M2$).

Now, the person-specific effect of T on Y is given by

$$B = \Gamma_1 \Delta_1^* + \Gamma_2 \Delta_2$$

Typically, we want to estimate $\delta_1 = E[\Delta_1]$ and $\delta_2 = E[\Delta_2]$. Given a multi-site trial, within each site s , we have

$$\beta_s = E[B|s] = E[\Gamma_1 \Delta_1^* | s] + E[\Gamma_2 \Delta_2 | s]$$

$$= \delta_{1s}^* \gamma_{1s} + \delta_{2s} \gamma_{2s} + Cov_s(\Gamma_1, \Delta_1^*) + Cov_s(\Gamma_2, \Delta_2)$$

Let us assume $Cov_s(\Gamma_1, \Delta_1^*) = 0$ and $Cov_s(\Gamma_2, \Delta_2) = 0$. The first of these says that the person-specific compliance of $M1$ is uncorrelated with the direct effect of $M1$ on Y . The second can be written as

$$\begin{aligned} Cov_s(\Gamma_2, \Delta_2) &= Cov_s(\Gamma_2^* + \Gamma_1 \Lambda_{12}, \Delta_2) \\ &= Cov_s(\Gamma_2^*, \Delta_2) + Cov_s(\Gamma_1 \Lambda_{12}, \Delta_2) \\ &= Cov_s(\Gamma_2^*, \Delta_2) + \gamma_{1s} Cov_s(\Lambda_{12}, \Delta_2) + \lambda_{12s} Cov_s(\Gamma_1, \Delta_2) \\ &\quad + \frac{1}{n} \sum [(\Gamma_1 - \gamma_{1s})(\Lambda_{12} - \lambda_{12s})(\Delta_2 - \delta_{2s})] \\ &= 0 \end{aligned}$$

This says that the person-specific effect of $M2$ cannot be correlated with any of the paths leading to it (and that the third centered moment of $\{\Gamma_1, \Lambda_{12}, \Delta_2\}$ must be zero, a condition that is met if the three terms are linearly related to one another and if each of them has a non-skew distribution). Thus, if the mediators are not parallel, then assumption (vi) must be expanded to include the assumption that the direct effect of any mediator cannot be correlated with any upstream pathway leading from the treatment to that mediator.

Given this assumption, we have

$$\begin{aligned} \beta_s &= \delta_{1s}^* \gamma_{1s} + \delta_{2s} \gamma_{2s} \\ &= \delta_1^* \gamma_{1s} + \delta_2 \gamma_{2s} + \omega_s, \end{aligned}$$

where $\omega_s = (\delta_{1s}^* - \delta_1^*) \gamma_{1s} + (\delta_{2s} - \delta_2) \gamma_{2s}$. As above, we require the assumption that this error term be independent of γ_{1s} and γ_{2s} :

$$E[\omega_s | \gamma_{1s}, \gamma_{2s}] = \gamma_{1s} \cdot E[(\delta_{1s}^* - \delta_1^*) | \gamma_{1s}, \gamma_{2s}] + \gamma_{2s} \cdot E[(\delta_{2s} - \delta_2) | \gamma_{1s}, \gamma_{2s}] = 0$$

A necessary, but not sufficient, condition for this to be true is that

$$Cov(\delta_{1s}^*, \gamma_{1s}) = 0$$

$$Cov(\delta_{2s}, \gamma_{1s}) = 0$$

$$Cov(\delta_{1s}^*, \gamma_{2s}) = 0$$

$$Cov(\delta_{2s}, \gamma_{2s}) = 0$$

The first two of these expressions indicate that the site-average compliance of mediator 1 is uncorrelated with the site average direct effects of both mediators 1 and 2. The third and fourth expressions can be written as

$$\begin{aligned} Cov(\delta_{1s}^*, \gamma_{2s}) &= Cov(\delta_{1s}^*, \gamma_{2s}^* + \gamma_{1s}\lambda_{12s}) \\ &= Cov(\delta_{1s}^*, \gamma_{2s}^*) + \gamma_1 Cov(\delta_{1s}^*, \lambda_{12s}) + \lambda_{12} Cov(\delta_{1s}^*, \gamma_{1s}) \\ &\quad + \frac{1}{S} \sum [(\delta_{1s}^* - \delta_1^*)(\gamma_{1s} - \gamma_1)(\lambda_{12s} - \lambda_{12})] \end{aligned}$$

and

$$\begin{aligned} Cov(\delta_{2s}, \gamma_{2s}) &= Cov(\delta_{2s}, \gamma_{2s}^* + \gamma_{1s}\lambda_{12s}) \\ &= Cov(\delta_{2s}, \gamma_{2s}^*) + \gamma_1 Cov(\delta_{2s}, \lambda_{12s}) + \lambda_{12} Cov(\delta_{2s}, \gamma_{1s}) \\ &\quad + \frac{1}{S} \sum [(\delta_{2s} - \delta_2)(\gamma_{1s} - \gamma_1)(\lambda_{12s} - \lambda_{12})] \end{aligned}$$

Thus, we require that the site-average direct effects of each mediator be independent of the site average compliance of each mediator and the site average effect of mediator 1 on mediator 2 (and that the third centered moment of $\{\gamma_{1s}, \lambda_{12s}, \delta_{2s}\}$ must be zero). In particular, we require $Cov(\delta_{1s}^*, \lambda_{12s}) = Cov(\delta_{2s}, \lambda_{12s}) = 0$.

Given these assumptions, and the ignorable treatment assignment and sufficient rank assumptions (assumptions viii and ix), we can identify δ_1^* and δ_2 from the regression

model

$$\beta_s = \delta_1^* \gamma_{1s} + \delta_2 \gamma_{2s} + \omega_s$$

because the β_s 's, γ_{1s} 's, and γ_{2s} 's are directly estimable from the observed data.

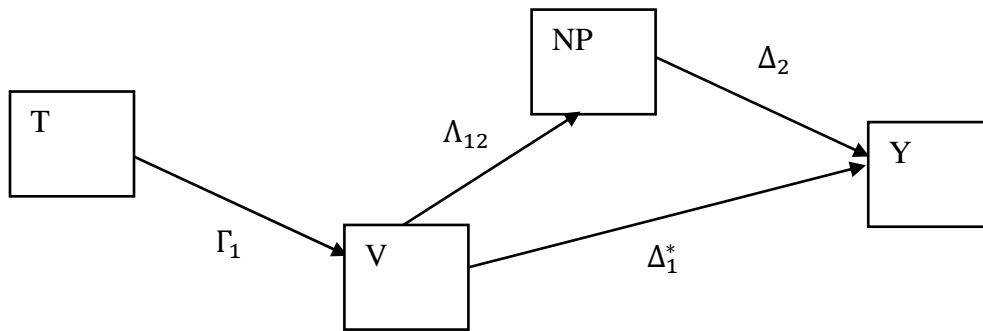
Importantly, however, the assumptions are not sufficient to identify δ_1 , the total effect of $M1$. Our assumptions imply that $\delta_1 = \delta_1^* + \lambda_{12} \delta_2$, but because our assumptions are, in general, insufficient to identify λ_{12} , we therefore cannot identify δ_1 . That is, if we replace the parallel mediators assumption with a stronger set of assumptions about the independence of the person-specific and site-specific direct effects of each mediator with everything upstream from that mediator, we still can only identify the direct effect of each mediator (that part of the effect that does not operate through any other mediator in the model).

In general then, if the mediators are not parallel, we require an additional set of assumptions in order to identify the direct effect of each mediator on the outcome. However, even if these assumptions are met, they are insufficient to identify the total effect of $M1$ on Y . To identify λ_{12} , we would require a further assumption regarding the independence of γ_{1s} and γ_{2s}^* .⁴

⁴ To see this, consider the lefthand part of Figure 1. If we consider $M2$ as the outcome, then T affects $M2$ both directly and through $M1$. Now construct a second mediator M^* that is in the direct pathway between T and $M2$. Let $M^* = T$ for all individuals, implying that Γ^* , the person-specific effect of T on M^* , is equal to 1 for all individuals, and that Δ^* , the person-specific effect of M^* on $M2$ is equal to Γ_2^* for all individuals. Now we have a case of parallel mediators— T affects $M2$ through two parallel mediators $M1$ and M^* . Assumption (vii) implies that γ_{1s} is independent of δ_s^* , but this is the same as assuming $\gamma_{1s} \perp \gamma_{2s}^*$. Thus, to identify λ_{12} , we require the additional assumption that the direct effects of T on both mediators are independent. Note that

It is useful to consider these assumptions in concrete terms. In the case of the MTO study analyzed in Katz, Kling, and Liebman (2007), random assignment to a voucher was hypothesized to affect outcomes via two potential mediators—use of the voucher and neighborhood poverty. Because neighborhood poverty could not be influenced except through use of the voucher, the implied structural model is this:

Figure 2:



In this model, treatment assignment affects neighborhood poverty (*NP*) only through use of a voucher (*V*). Both *NP* and *V* may then affect an outcome *Y*. Our discussion above implies that identification of δ_2 requires two key sets of assumptions. First, within each MTO site *s*, a family’s likelihood of using the voucher if offered it and the change in neighborhood poverty experienced by a family if they use the voucher are uncorrelated with the effect of neighborhood poverty on that family. Families for whom a move to low-poverty neighborhoods would be particularly beneficial are no more likely to use the

nowhere else have we assumed that compliances are uncorrelated; this is a strong, and generally untenable, assumption.

voucher and move to low-poverty neighborhoods than are families for whom such a move would be less beneficial. Second, across MTO sites, there are no correlations between a) the average impact of neighborhood poverty and average voucher take-up rate; b) the average impact of neighborhood poverty and the average impact of voucher use on neighborhood poverty rates ; c) the average impact of using of a voucher and the average voucher take-up rate; or d) the average impact of using of a voucher and the average impact of voucher use on neighborhood poverty rates. If, for example, sites where the use of a voucher had a large impact on neighborhood poverty (because it was relatively easy for families to move far from their original neighborhood) were also sites where use of a voucher moved families far from family and friendship networks that have a positive effect on outcomes, then the assumption of the independence of the direct effect of the voucher (through network supports in this example) and the effect of one mediator on another would be violated. Note that, in the MTO example, it would be possible to identify the total effect of the first mediator (use of the voucher), because there is no pathway from T to Y that does not go through V . Identifying the effect of NP and the direct effect of V on Y , however, requires additional assumptions about the independence of these effects and the effect of V on NP . Given the correlation of neighborhood poverty and other factors likely to influence the outcomes of interest in the MTO study, such assumptions may not be warranted.

The Site-Average Compliance-Effect Independence Assumption

The assumption that the site-average compliances are independent of the site-average effects is non-trivial. Because site-average compliance effects are not randomly

assigned to sites, they may not be independent of the site-average mediator effects.

Consider a simple example. Suppose we have a multi-site study of the impacts of welfare-to-work programs, as in Duncan, Morris, and Rodrigues (forthcoming), where the programs are hypothesized to affect child outcomes by affecting mothers' hours worked, income, and welfare receipt. Suppose that entry-level wages and the cost of living are higher in some sites than others. In this case, randomized assignment to a training program may induce a greater increase in hours worked and income (higher compliance) in high-wage sites than in low-wage sites (because the wage benefits of work are greater); however, the effect of increased income on child achievement may be lower in high-wage sites than in low-wage sites, because the cost of child care, preschool, and school quality is higher. Such a pattern would induce a negative correlation between the work and income effects of the program and the effects of income on children, violating the assumption of site-average compliance-effect independence.

Although the compliance-effect independence assumption is not empirically verifiable, it may be falsifiable, given sufficient data. For example, in a multi-site study with a single mediator and in which each of the nine assumptions are met, a plot of the site-average intent-to-treat effects (the β_s 's) against the site-average compliance effects (the γ_s 's) will display a pattern of points scattered (with variance proportional to the square of γ_s) around a line passing through the origin with slope equal to δ , the average effect of the mediator. A violation of the site-average compliance-effect independence assumption, however, will render the expected scatterplot non-linear. With sufficient data (a sufficient number of sites and sufficiently precise estimation of the β_s 's and γ_s 's for each site), one might have adequate statistical power to reliably detect such non-linearity, allowing one to

reject the compliance-effect independence assumption. With multiple mediators, the same logic would apply, albeit in a multidimensional space and requiring commensurately more data.

The Sufficient Rank Assumption

The sufficient rank assumption is relatively straightforward. In order to identify the effects of P mediators using an MSMM-IV model, we require at least as many sites as mediators; we require that the effect of treatment assignment on the mediators varies across sites (for at least $P - 1$ of the mediators); and we require that there are at least P sites among which these effects are linearly independent. In many practical applications, these assumptions are likely to be met. The average effect of treatment assignment on a mediator is likely to vary across sites for a variety of reasons, including differential implementation, heterogeneity of populations, and differences among sites in baseline conditions or capacity. Moreover, unless the mediators are conceptually very similar, the effects of treatment assignment on the mediators are unlikely to be perfectly collinear.

Nonetheless, in practical applications, the effects of treatment assignment on the mediators are likely to be somewhat correlated (though not perfectly) across sites. This may occur because in sites where a treatment is well-implemented, the treatment may affect all mediators more than in sites where it is poorly implemented. Or it may occur because the mediators are correlated in the world, leading to a correlation of compliances. For example, because income is correlated with hours worked, sites in which a treatment—such as a welfare-to-work experiment—induces large changes in hours worked will tend to also be sites in which the same treatment induces large changes in income.

Although such correlations among the γ_s 's do not pose an identification problem for the MSMM-IV model (we require no assumption regarding the independence of the site-average compliances), they may pose a problem for estimation. Because the identification of the effects of the mediators depends on the separability of the site-average compliances, statistical power will be greatest—all else being equal—when compliances are not positively correlated.

6. CONCLUSION

If each of the nine assumptions described above are met, the effects of each mediator are, in principle, identifiable from observed data. Such models provide a possible approach to estimating the effects of the mediators of treatment effects when such mediators cannot themselves be easily assigned at random. The assumptions necessary for consistent identification in MSMM-IV models are not, however, trivial. In addition to the usual IV assumptions, such models require several additional assumptions. The parallel mediator and site-average compliance-effect independence assumptions, in particular, are relatively strong, and cannot be empirically verified. Justification of such models must rely, therefore, on sufficiently strong theory or prior evidence to warrant these assumptions.

Although we have framed our discussion in the context of a multi-site randomized trial, where 'sites' are specific locations (different cities in the MTO example, different studies and cities in the welfare-to-work example), the same logic would apply to any study in which randomization occurs within identifiable subgroups of individuals. Thus, one could stratify the sample of a large randomized trial by sex, age, and race, and treat each sex-by-age-by-race cell as a 'site' in order to create multiple 'site'-by-treatment interactions

as instruments. This would, in principle, allow one to identify the effects of multiple mediators within a single (large) randomized trial, but only under the set of assumptions we describe above. Alternately, one could estimate a set of propensity scores, indicating each individual's 'propensity to comply' with each mediator, and then stratify the sample by vectors of these propensity scores. Using such strata as 'sites' in an MSMM-IV model would have the potential advantage of creating strata in which the site-average compliances are uncorrelated, which may increase the precision of the estimates.

Several important issues remain to be addressed in order to fully understand the use of MSMM-IV models. First, although failure of the assumptions will lead to inconsistent estimates, it is not clear how severe the bias resulting from plausible failures of the parallel mediators and compliance-effect independence assumptions will be. Second, we have not discussed the properties of specific estimators of MSMM-IV models or the computation of standard errors from such models. Both issues merit further investigation.

Finally, although the nine assumptions we outline above ensure the consistent estimation of the effects of multiple mediators, they do not ensure unbiased estimation in finite samples. In single-site single-mediator instrumental variables models, finite sample bias is a concern when the average compliance is small relative to its sampling variance. In multiple-site, multiple-mediator models, finite sample bias is more complex. In general, however, finite sample bias is likely to be a concern when both the average compliance (across sites) is small and the variance of the site-average compliances is small, relative to the sampling variation of the site average compliances. A full discussion of finite sample bias is beyond the scope of this paper, however.

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